The EASIS Security Architecture Approach



Thomas Eymann, Robert Bosch GmbH

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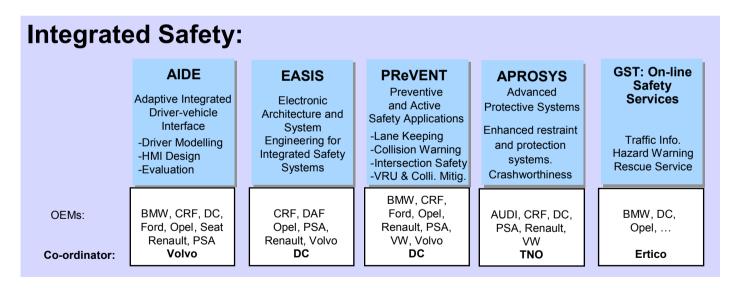






Motivation

- > The European Union set the target to halve the number of mortal accidents until 2010
- > Promotion of the EUCAR programme "Integrated Safety" in the 6 FP of the European Union
- ➤ The EASIS¹ Project is a part of the EUCAR Programme "Integrated Safety"



) ¹ Electronic Architecture and System Engineering for Integrated Safety Systems







Project Data



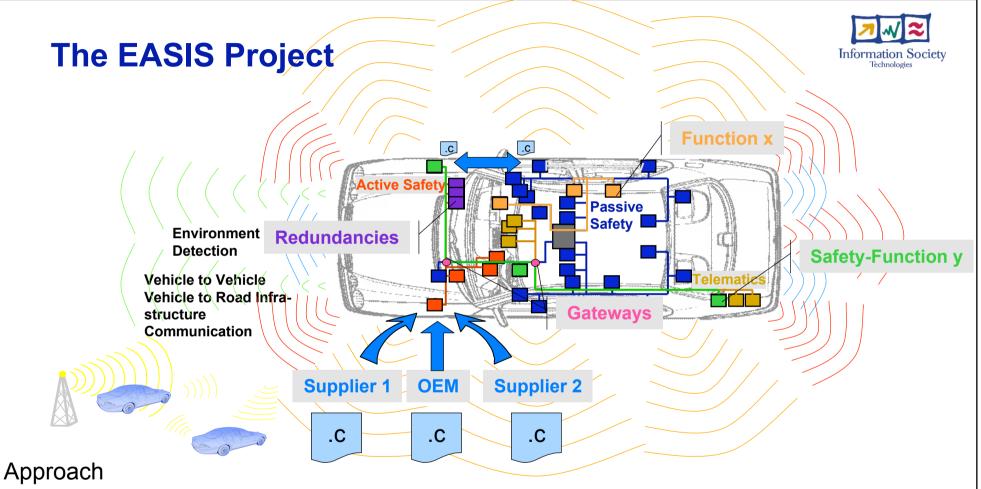
- Project duration: 01.2004 03.2007
- > Total budget 9,4 M€ / Funds 5 M€
- Project Partners

DaimlerChrysler, DAF Trucks, Centro Ricerche FiatOpel, PSA, Renault, Volvo Bosch, ContiTeves, Lear, Motorola, Philips, Valeo, ZF DECOMSYS, dSPACE, ETAS, Vector Offis, MIRA, University Duisburg/Essen

Core Group DaimlerChrysler, Bosch, Centro Ricerche Fiat, Valeo, Volvo and ZF







Develop a standardised in-vehicle electronic architecture and a standardised system engineering approach for integrated safety systems Provide an enabling technology for the introduction of integrated safety systems

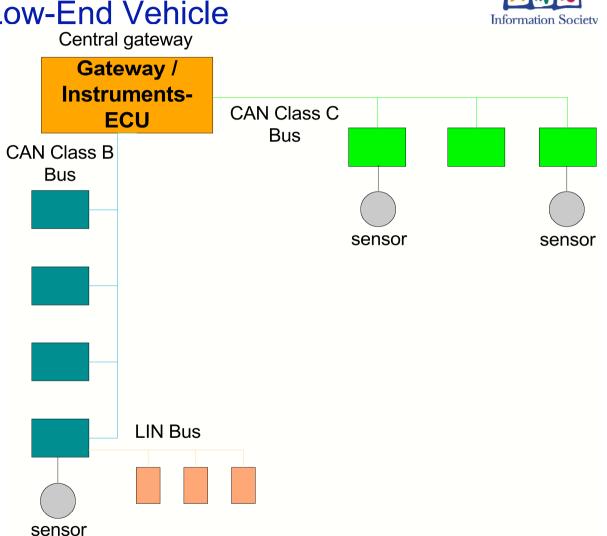






Network Architecture: Low-End Vehicle

 Diagnosis via direct connection at the Gateway-/Instruments-ECU









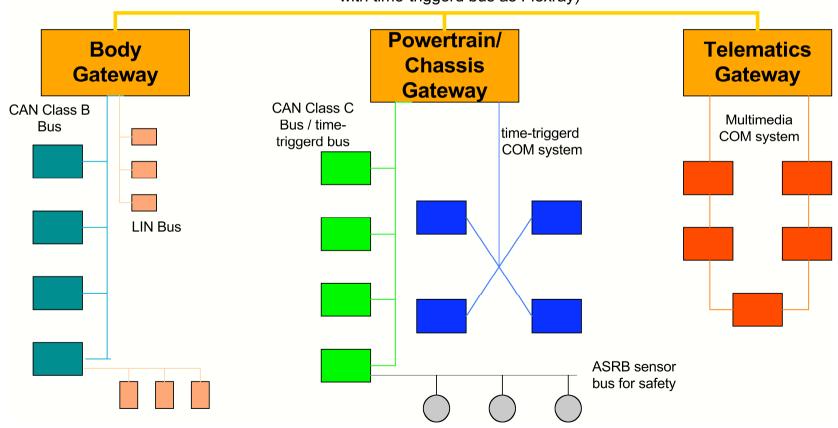
Network Architecture: High-End Vehicle



Distributed Diagnosis

Domain

Backbone (high bandwidth communication system with time-triggerd bus as Flexray)







EASIS Communication Possibilities



- EASIS defines four communication relations between possible communication entities (Integrated safety applications or systems):
 - Exchange of information with
 - other Vehicle (e.g. Vehicle-to-vehicle)
 - the infrastructure (e.g. vehicle-to-road-side-unit, Commercial service providers)
 - Inter-domain communication
 - protocol conversion (e.g. signal conversion)
 - end-to-end (e.g. common transport protocol)
- Safe and reliable communication is needed
- Safe and reliable SW and HW implementation is needed



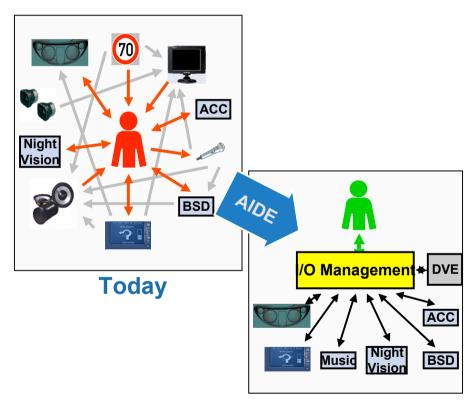




Application I



- Adaptive Integrated Drivervehicle Interface (AIDE)
 - Adaptation of the HMI-output to the strain state of the driver
 - Access to the car sensors, ACC, traffic and road data in the different car domains is needed
- Safe and reliable communication is needed



Vision





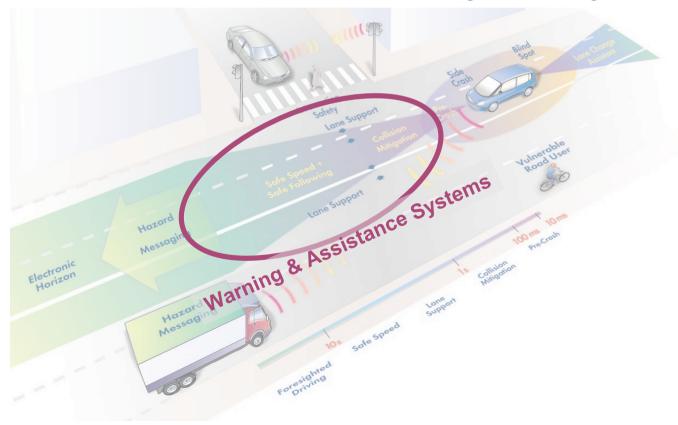
Application II



PReVENT sub-project Willwarn (Wireless Local Danger Warning)

Expansion of the detection horizon of the driver thank to warning about danger

sources







Attacks



- Eavesdropping
 - Eavesdropping and recording of a warning message (warning about emergency vehicles)
- Denial of Service
 - Accessibility of a service is restricted
- Bogus information attack
 - Faking of a warning message
- Spoofing
 - Take over of the identity of an authorised device (cone, speed limit)
- > ID disclosure of other vehicles
 - Surveillance of the vehicle motions by using the V2V and V2I infrastructure

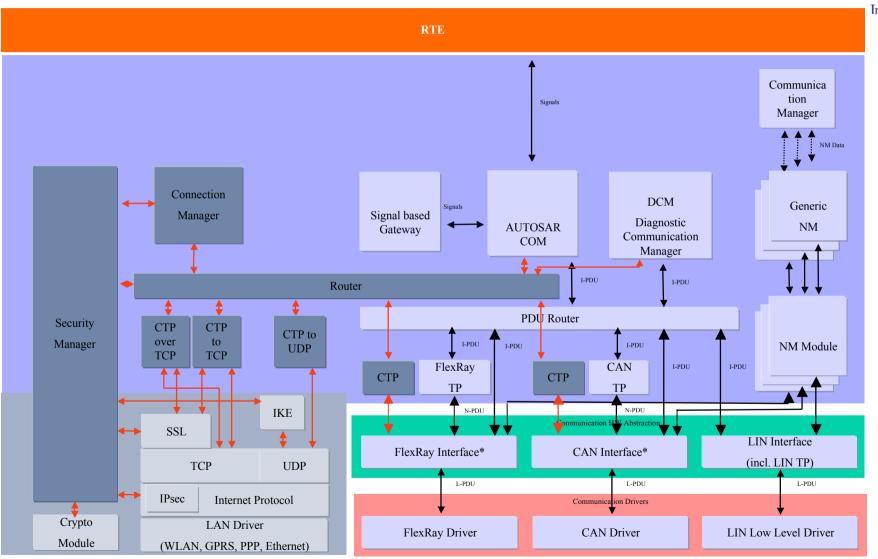






EASIS Gateway Architecture

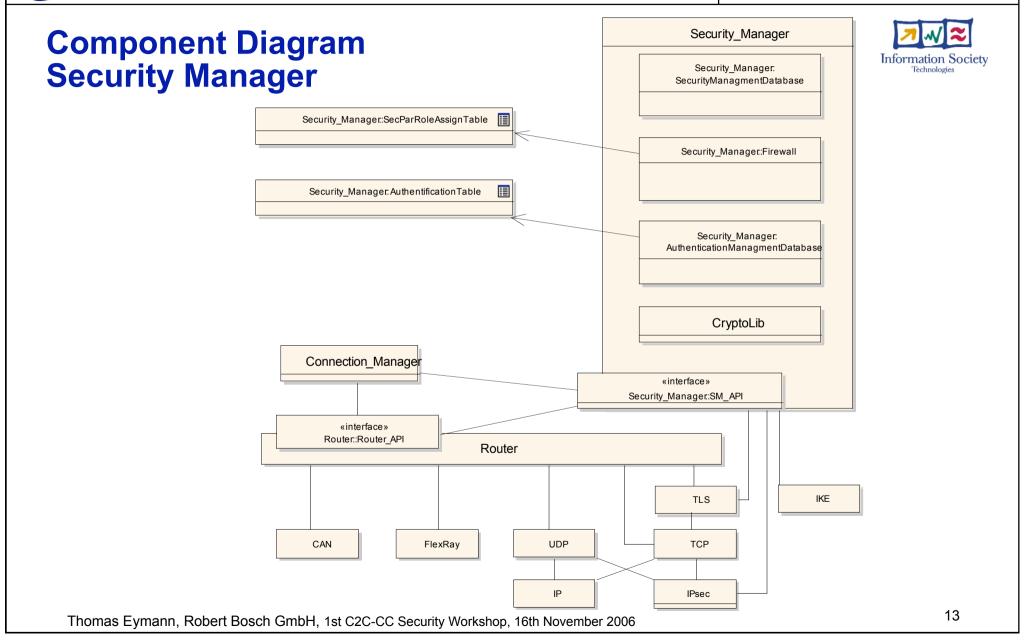




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Component Diagram Security Manager (1)



Firewall

 Provides filtering rules for the access control to car-internal communication entities

 Determines the required security processes for the external connection establishment

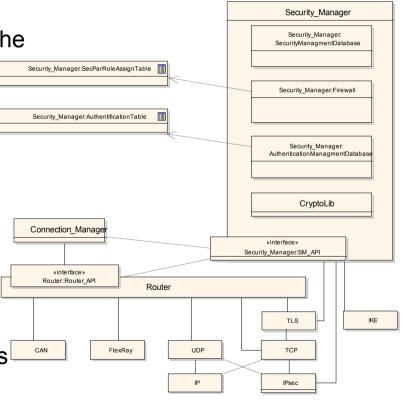
Security Parameter Assign Table

(SecParRuleAssignTable)

- Assignment of the security parameters to a role
- Parameters: protocol type, min. authentication, hash and encoding process, target and source address

CryptoLib

Wrapper in order to use different Crypto modules





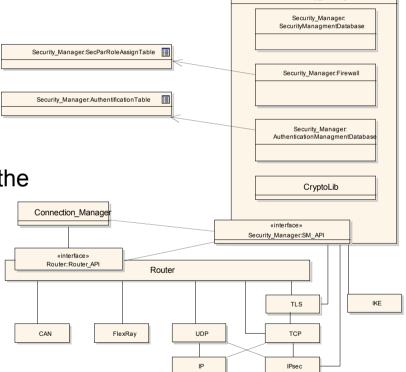


Component Diagram Security Manager (2)



Security Manager

- Authentication Management Database (AMD)
 - Management of the own certificates
 - Reliable recording of root certificates
 - User database incl. roles, public keys etc.
- Security Management Database (SMD)
 - Management of current connection data and of the security parameters
 - Communication partners
 - Authentication method
 - User and current role
- Security Management API (SM_API)
 - interface between security manager and external components



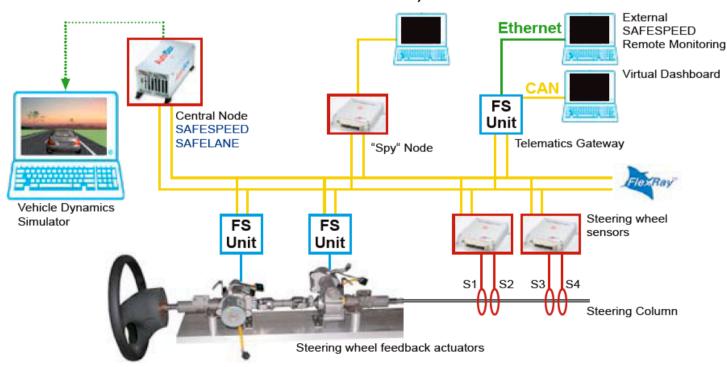




EASIS Validator:



- It includes a Telematics Gateway between internal buses (fault-tolerant FlexRay network and CAN network) and external Telematics network (WLAN/Ethernet) with protocol conversion and security services
- It includes two demonstrative applications:
 - SAFESPEED (adaptive vehicle speed to maximum allowed speed)
 - REMOTE MONITORING (web server delivering information such as vehicle speed or vehicle status to authorized users)





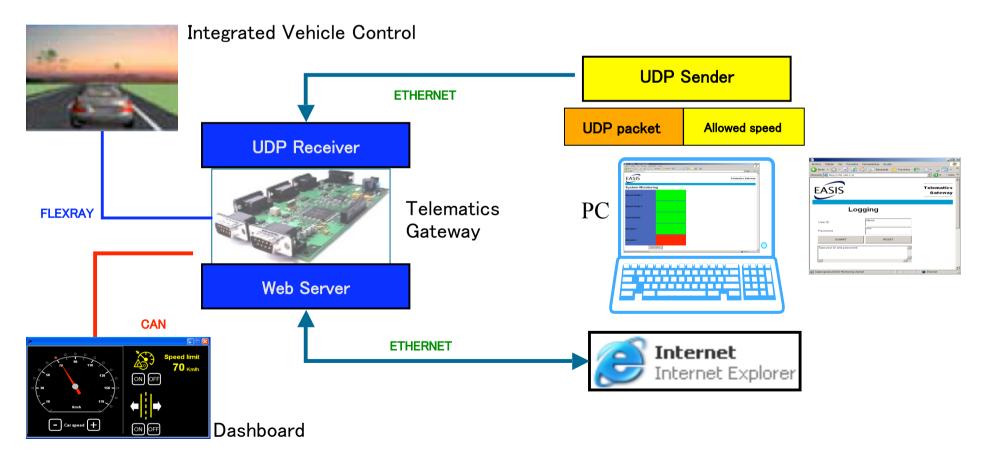




Telematics Gateway:

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- It integrates an scalable implementation of TCP/IP protocol
- > It integrates a UDP sender / receiver for SAFESPEED
- It integrates a WEB server for REMOTE MONITORING with authentication & authorization
- It integrates a gateway with automotive buses FlexRay and CAN







Summary

- Integrated safety systems and similar applications require reliable communication over the domains
- A security management Architecture based on the AUTOSAR approach has been presented:
 - Use of a rule-based access control for internal and external communication
 - Protection of the external communication by means of the standards IPsec, IKE und TLS/SSL, established in the internet.
 - Protection of the internal communication at the transport layer level is made possible (CTP protocol)
 - Modular architecture allows a simple expansion of security standards (e.g. for V2V, V2I)
- Basic concepts has been demonstrated by the EASIS validator





Thank you very much for your attention



Are there any questions?